



PROMATION ENGINEERING

Precision Actuation for Industry

Installation & Operation Manual

This IOM is for the following
ProMation Engineering Products:

P7-120PN4-HR

P7-230PN4-HR

P8-120PN4-HR

P8-230PN4-HR

P7S-120PN4-HR

P7S-230PN4-HR

P8S-120PN4-HR

P8S-230PN4-HR

Valid for the following Options

- TS - Torque Switch equipped
- 68 - IP68 compatible enclosure
- SS - Stainless Steel enclosure



**PROMATION
ENGINEERING**
Precision Actuation for Industry

Field Manual

P7,8(S) HV-PN4-HR (-TS)

High Resolution Proportional Control Powered Feedback ISO5211 F12 8P36

Imperial Mount S 5in/6 BHC
P7 1.375in Shaft, 0.3125 in sq key
P8 1.625in Shaft, 0.375 in sq key



ISO 5211 Mount Shown

Actuator Sizes and Voltage Options

Product Family	Torque Output		Voltage Options				
	in lbs	Nm	12DC	24DC	24AC	120AC	230AC
P2	800	90	✓	✓	✓	✓	✓
P3	1,335	150	✓	✓	✓	✓	✓
P4	3,500	400	✓	✓	✓	✓	✓
P5	4,400	500	✓	✓	✓	✓	✓
P6	5,750	650	✓	✓	✓	✓	✓
Actuators In This IOM							
P7	8,900	1,000		✓	✓	✓	✓
P8	13,250	1,500		✓	✓	✓	✓
P9	17,500	2,000				✓	✓
P10	22,000	2,500				✓	✓
P11	26,500	3,000				✓	✓
P12	31,000	3,500				✓	✓
P13	40,000	4,500				✓	✓

FM_P213 ISO HV-PN4-HR (-TS) NZ_Ver Q 080223

Product Specifications

These may be equipped with internal torque switches (-TS) which protect the gear train, motor and controlled equipment from damage when high torque conditions exist.

These protective devices are NOT adjustable. More information on this technology is found throughout this manual.

Actuator Specifications	P7		P8	
Torque "lb/Nm	8900"lbs/1000Nm		13250"lbs/1500Nm	
Supply Voltage	120vac	230vac	120vac	230vac
Max Inrush Current	8.5A	4.1A	9.0A	4.4A
Running Current	3.1A	1.4A	3.3A	1.6A
Motor	Split Phase Capacitor			
Runtime (90°@60Hz)	46 sec		46 sec	
Runtime (90°@50Hz)	55 sec		55 sec	
Duty Cycle	25%, Proportional: Managed (75% maximum)			
Motor Starts	1200 per hour			
Weight	82lbs/37kg			
Mechanical Connections	ISO5211 F12 8pt 36mm			
Electrical Entry	(2) 3/4" NPT			
Electrical Terminations	12-16ga			
Environmental Rating	NEMA 4/4X			
Manual Override	11.6" Handwheel			
Control	On/Off-Jog, Proportional			
Actuator Case material	Aluminum Alloy, Powder coated			
Motor Protection	230°F/110°C Thermal F* Class *Totally Enclosed Non-Ventilated Motors			
Ambient Temperature	-22°F to +125°F			
Operating Range	-30°C to +52°C			

Introduction

This document provides necessary information for set-up, calibration, testing and use of the P Series quarter-turn electric actuators stated on the cover page. Each unit is shipped from the factory with initial calibration of mechanical stops, cams and switches completed for 0-90 degree operation. However, these are general settings and serve as a starting point for proper calibration of the actuator in its real-world application.

Safety

Safety is a basic factor any time you maintain and operate mechanical equipment. Appropriate handling methods and proper use of tools and personal protective equipment (PPE) can help prevent serious accidents which can cause injuries to you or a fellow worker. This manual was created to enable a trained user to install, adjust and troubleshoot your ProMation actuator.

Only competent and trained personnel should install, maintain and operate ProMation actuators. Any work related to this actuator must be carried out in accordance with this manual and related codes and regulations. Local workplace health and safety rules must always be followed.

Duty cycle

Duty cycle is the percent of time that an actuator spends running as a fraction of the total time. Duty Cycle is directly related to heat; excessively repositioning an actuator typically results in motor overheating which can cause permanent damage and/or reduced service life.

Duty cycle can be calculated as follows:

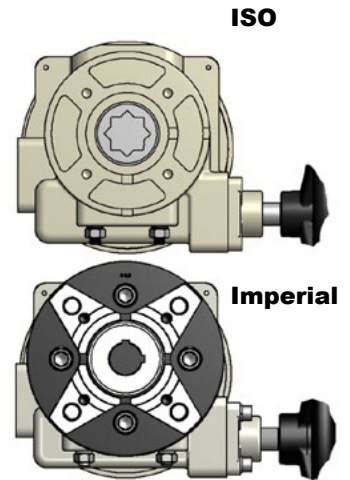
(example P2 series actuator running 3 seconds ON and 30 seconds OFF)

Runtime = 3s, Total time = 3s + 30s = 33s, therefore this duty cycle would be 9% (3/33)

Additionally, ProMation P series actuators are designed for a maximum of 1200 starts per hour (one start every 3 seconds maximum).

Shipping and Handling

1. This actuator is shipped in the FULLY CW position (2 color position indicator shows "CLOSE" and the Reference Dimple aligns with "0").
2. **NOTE, THIS ACTUATOR MUST HAVE WATER TIGHT EMT FITTINGS, WITH CONDUIT DRAINAGE INSTALLED AND POWER SUPPLIED TO UNIT TO KEEP THE HEATER WARM AT THE TIME OF INSTALLATION.**
3. **Storage: This unit should NOT be stored outside unless it is powered up and has proper conduit terminations. When NOT powered up, it should be stored in a clean, dry environment at all times.**
4. This actuator has been **factory calibrated to operate between 0 degrees and 90 degrees. Most quarter-turn products will not require recalibration of these settings.** If any travel adjustment is necessary, please refer to page 10. Cam adjustments instructions, pages 6-7 are included for reference only -- **the proportional controller should be used for any changes to positioning.**
5. **The actuator CANNOT operate with a rotation greater than 95 degrees.**



Product Mounting and Setup

1. Fully CLOSE the valve or damper to which the actuator is to be mounted.
 - Keep in mind this actuator rotates CW (as viewed from above the unit) when driving CLOSED.
2. Assemble necessary linkage components and attach the actuator to the driven device.
3. Tighten mounting bolts, making sure actuator is centered on the device drive shaft.
4. Utilize the handwheel to check for unobstructed manual operation from fully CCW to fully CW positions BEFORE applying power to the unit.
5. Make the electrical connections per wiring diagram on page 4.
 - Connect POWER to terminals marked 1 and 2 on the switch card (430-10100).
 - Connect CONTROL to (DHC-100 J2) terminals marked 4 and 5 OR 4 and 6 per Wiring Diagram on page 4.
 - Terminals 7-12 on the switch card (430-10100) can be used for the (adjustable) aux switches. They are dry type Form C rated 10A @ 250vac MAX.
6. Do NOT apply power at this time.

Installation Notes

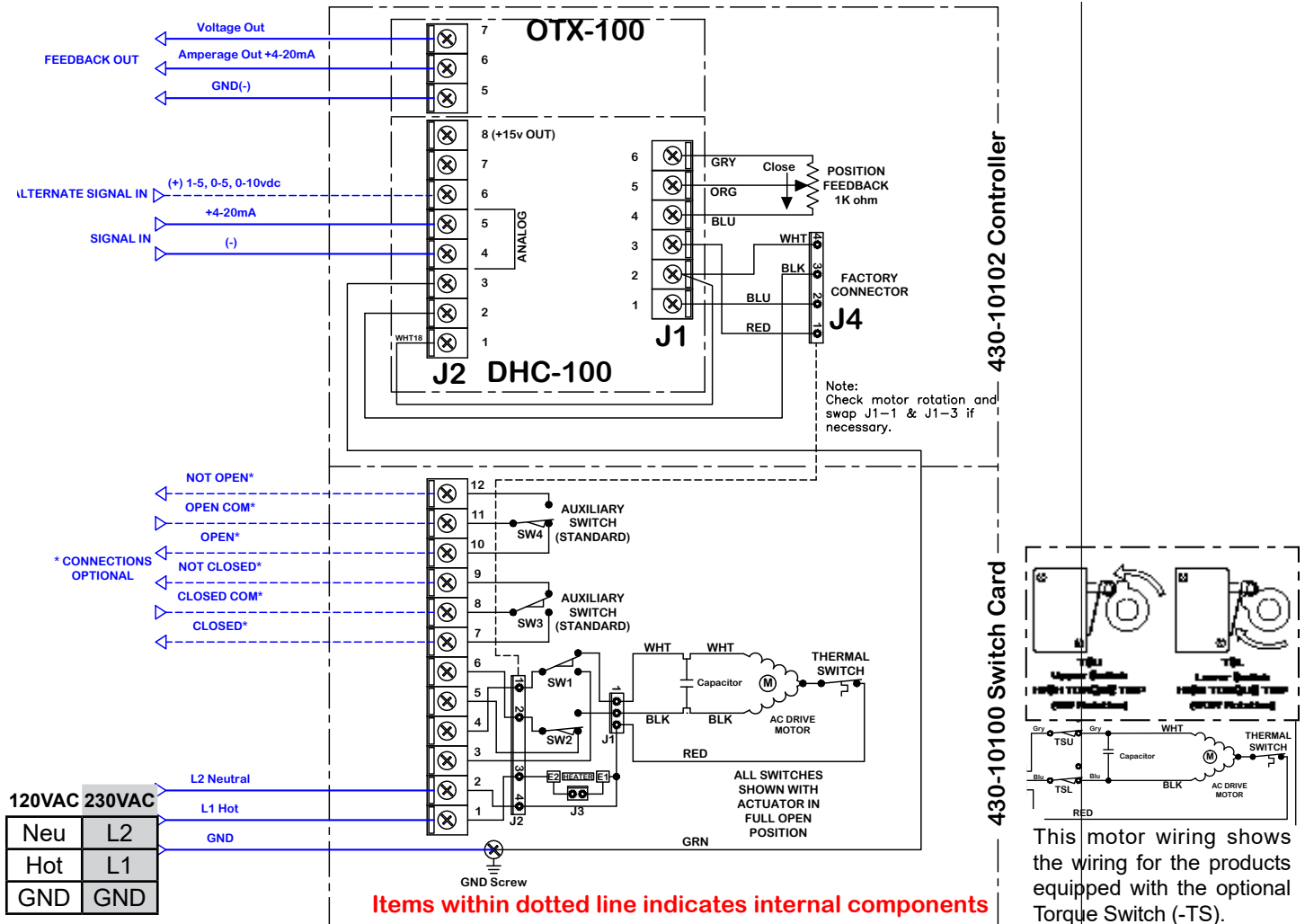
- These actuators are designed to be used between a horizontal and upright position. Do NOT mount the assembly with the actuator top below a horizontal position.
- When installing conduit, use proper techniques for entry into the actuator. Use drip loops to prevent conduit condensate from entering the actuator.
- Mechanical travel stops are factory calibrated for 90 degree operation. These stops are NOT designed to adjust mechanical rotation by more than +/- 3 degrees, they are for positioning the handwheel only.
- Both NPT conduit ports MUST use proper equipment to protect the NEMA 4X integrity of the housing.
- The internal heater is to be used in ALL applications.
- Do NOT install the actuator outdoors or in humid environments unless it is powered up and the heater is functioning.
- Use proper wire size to prevent actuator failure (see chart on page 4 for proper wire sizing).
- All terminals accept 12-16AWG solid/stranded wire.



Identifying Torque Switch Units:

- -TS in Product Name on label.
- Units with Torque Switches have additional switches mounted on the motor plate (see photo).

FM_P213 ISO HV/FPN4-HR (-TS) NZ_Ver Q 080223



Field wiring and devices by others

Torque Switches (if equipped)

For units equipped with torque switches: Torque switches provide mechanical overload protection for both the actuated device and the geartrain.

These are factory set and are not adjustable without proper equipment. Torque switches are set to limit actuator torque to approximately 105% of the actuator rated output.

The wiring diagram above shows the internal wiring connections between the control board, the torque switches and the motor. The upper torque switch controls loading in the CW direction, while the lower switch controls loading in the CCW direction.

WARNING! Do NOT adjust the torque switch cam settings. This will VOID the warranty.

Wire sizing data is provided in the table to assist in the selection of the proper wire size for ProMation actuators using various wire sizes over distance.

Please make sure to reference the correct voltage and do not exceed the indicated length of the wire run for each model.

Wire Sizing Chart

Actuator	MAX distance between Actuator and Supply (feet)			
	P7		P8	
Voltage	120VAC	230VAC	120VAC	230VAC
Wires Gage	8.5A	4.1A	9.0A	4.4A
16	-	607	-	566
14	247	981	233	914
12	377	1500	357	1398
10	642	2550	606	2376
8	958	3806	905	3546

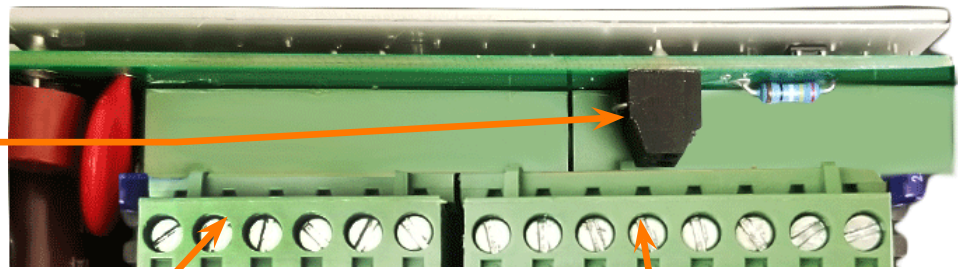
This motor wiring shows the wiring for the products equipped with the optional Torque Switch (-TS).

Diagram of Controller

Proportional Control

The AC Controller Shown. Calibration sequence is the same for both AC and DC

J7 Connector



J1 Connector

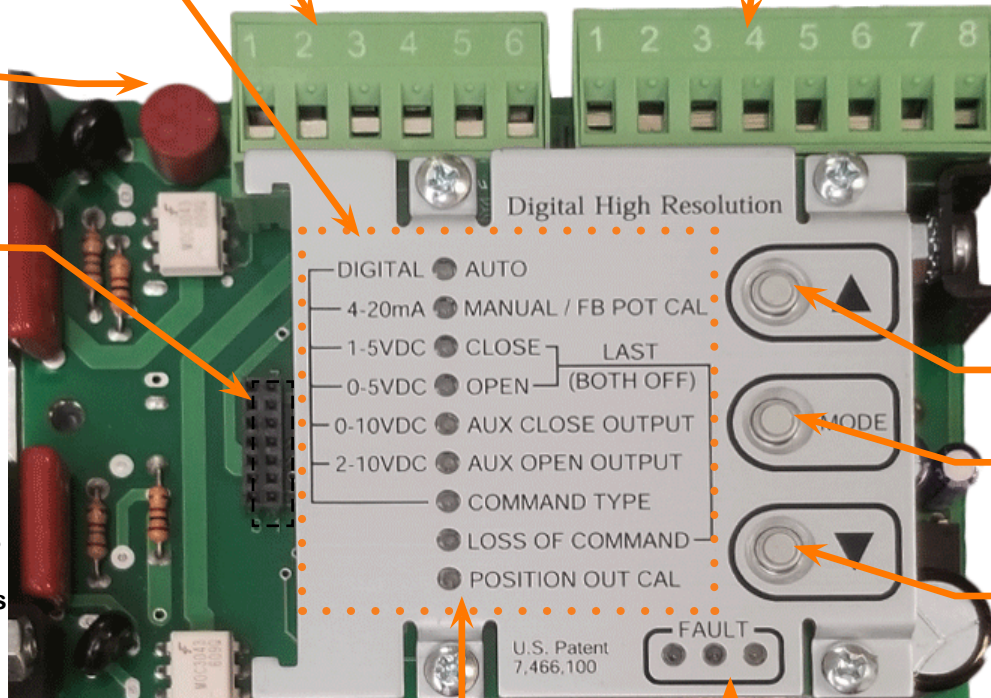
J2 Connector

Calibration Menu

Fuse

J3 Connector for Optional Feedback or Modbus Control Options

For MODBUS control parameters, see [ProMation Modbus prmtrs 800-192B.pdf]



Select ▲ Button

MODE Button

Select ▼ Button

Calibration LED Indicators

Fault LED Indicators

This proportional control card has been calibrated and tested at the factory to operate between 0 degrees and 90 degrees operating range. Controller position settings control the actuator, adjustment of cam settings may affect controller operation, resulting in a fault.

The Default Settings of the controller are as follows:

- Input Signal: 4-20mA (may be changed)
- Output Signal: 4-20mA (cannot be changed)
- Signal Response: Direct Acting (open = CCW)
- Loss of Command: Fail in Position

Input Signal Options:

- 4-20mA (default)
- 1-5vdc, 0-5vdc, 0-10vdc (Wire as shown on page 4, J2, terminal 6 and select Command Type from Calibration Menu.)

Fault Detection:

- Fault Indicator will flash and motor outputs are turned off until all faults are corrected.
- All Faults show on the same LED
- See Fault Table for priority listing of faults

Controller Notes:

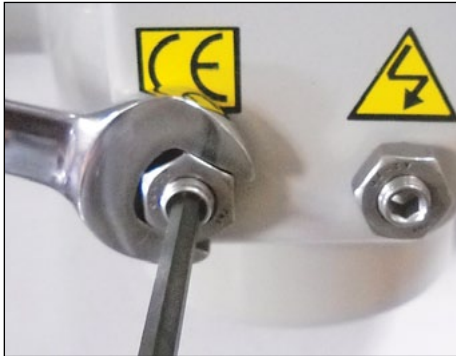
- Limit (Cam) Switches (SW1 and SW2) can cause a Motor Stall Fault if set too close to the 0° (CW) or 90° (CCW) positions.

F:\Module\FP2\F2\FANS_Calibration\F2-HR-0100\F2A\K1@340028R\STER.indd

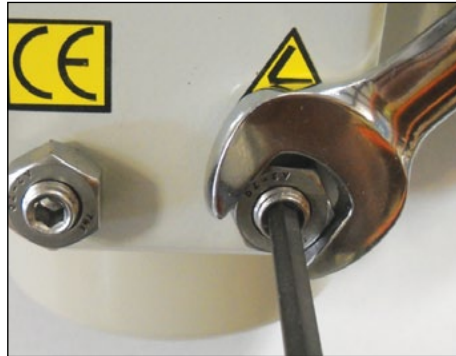
Setting Limit Switches and Auxiliary Switches (Cams)

This actuator has been factory calibrated to operate between 0 degrees and 90 degrees. Proportional Controller positioning changes different from 0 and 90 degrees will likely involve also changing cam settings. If cam adjustments cause the controller board to show faults, you will need to reposition the cam further outside your range of travel. Back out the mechanical stops before making any cam setting change so the gear train does not strike a mechanical travel stop.

Serious Damage to the actuator will result if the motor is allowed to drive the gear train into the mechanical stop!! Be sure the mechanical stops are out before making adjustments.



CCW Mechanical Stop
OPEN, 90°, 20mA, Green Cams



CW Mechanical Stop
CLOSE, 0°, 4mA, Red Cams



Mechanical Stop
Adjustment Positions

The mechanical stop screws limit handwheel operation ONLY and are NOT to be used as an electrical travel limiting device.

Loosen Mechanical Stops

- BEFORE power is applied, use a 17mm wrench and a 5mm hex key to loosen the LEFT and RIGHT SIDE mechanical stops.
- Turn the stop screws 5-6 turns CCW to allow electrical cam stop adjustment to keep the internal stops from running into the mechanical stop screws.
- Leave the stop screws out until controller calibration is complete.



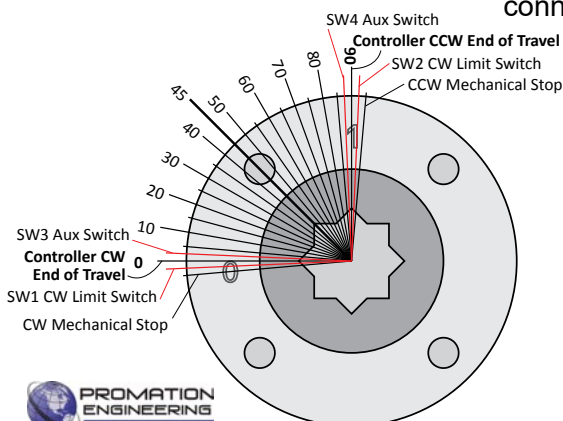
Cam 4
Cam 3
Cam 2
Cam 1

Understanding Cam Operation

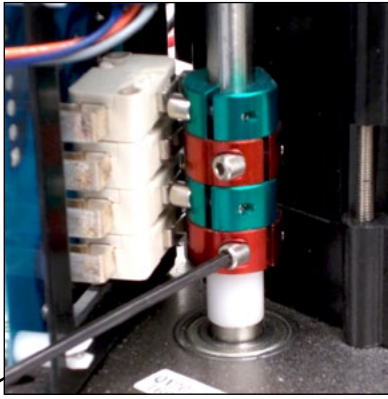
- The lowest cam, Cam 1 controls SW1, a CW limit switch secondary to the controller board. It will interrupt power to the board and motor if it changes state and shows as a fault on the controller board.
- The second cam, Cam 2 controls SW2, a CCW limit switch secondary to the controller board. It will interrupt power to the board and motor if it changes state and shows as a fault on the controller board.
- The third cam, Cam 3 controls SW3, a CW (CLOSED) auxiliary switch connected to the optional outputs 7-9 of the 430-10100 Switch Card.
- The uppermost cam, Cam 4 controls SW4, a CCW (OPEN) auxiliary switch connected to the optional outputs 10-12 of the 430-10100 Switch Card.

Practical Cam Considerations

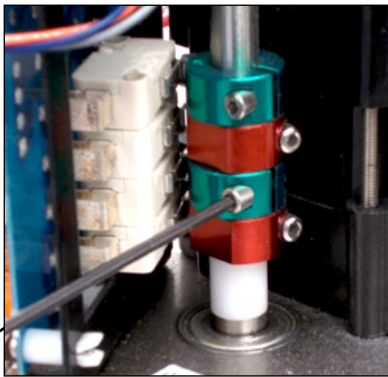
- SW1 and SW2 can be used as electrical limit switches. For proper function their cams must be set outside (or beyond) the CLOSE and OPEN positions of the proportional controller.
- SW1 and SW2 do not impact initial controller calibration unless their cams are set within controller travel limits.
- After changing any cam settings, test the actuator limits for proper functionality.



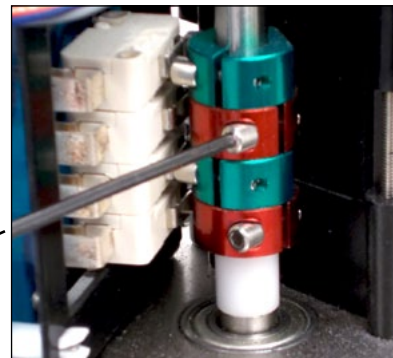
Cam Adjustments



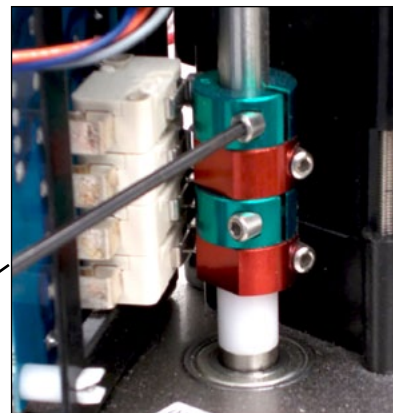
Cam 1



Cam 2



Cam 3



Cam 4

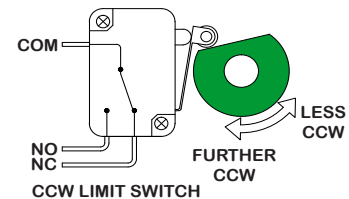
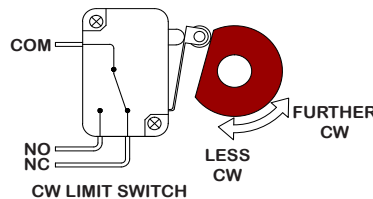
Listed here for reference. Mechanical stops must be out before changing cam settings. Proceed ONLY if adjustments are required.

Adjust Cam 1 (SW1 -- CW limit switch)

1. The lowest cam is Cam 1, the CW limit switch (SW1) cam. Once the actuator is at its required CW position turn POWER OFF. Use the handwheel to drive more CW by 1-2°. Use a 2.5mm hex key to free up the cam set screw. Once it is free, rotate the hex key to the RIGHT 10-15 degrees to reset the switch roller arm. Then snug the set screw up against the camshaft (CW) until slight pressure is felt. Then SLOWLY rotate the hex key pushing the cam to the LEFT until you hear the “click” on the bottom switch indicating that correct adjustment has been achieved. Tighten the set screw.
2. Use the handwheel to check to be sure this is the correct CW position you require (refer to Page 6). Repeat step 1 if further adjustment is needed.

Adjust Cam 2 (SW2 -- CCW limit switch)

1. The second cam is Cam 2, the CCW limit switch (SW2) cam. Once the actuator is at its required CCW position turn POWER OFF. Use the handwheel to drive more CCW by 1-2°. Use a 2.5mm hex key to free up the cam set screw. Once it is free, rotate the hex key to the LEFT 10-15 degrees to reset the switch roller arm. Then snug the set screw up against the camshaft (CW) until slight pressure is felt. Then SLOWLY rotate the hex key pushing the cam to the RIGHT until you hear the “click” on the second switch indicating that correct adjustment has been achieved. Tighten the set screw.
2. Use the handwheel to check to be sure this is the correct CCW position you require (refer to Page 6). Repeat step 1 if further adjustment is needed.



Adjust Cam 3 (SW3 -- CW auxiliary switch)

1. The THIRD cam is Cam 3, the CW auxiliary switch (SW3) cam. When the actuator is in its CW position set this cam. Use a 2.5mm hex key to free up the cam set screw. Once it is free, rotate the hex key to the RIGHT 10-15 degrees to reset the switch roller arm. Then snug the set screw up against the camshaft (CW) until slight pressure is felt. Then SLOWLY rotate the hex key and cam to the LEFT until you hear the “click” on the third switch. Continue to rotate the cam between 3 and 5 degrees to the LEFT to make sure the auxiliary cam switch changes state before the actuator reaches its end of travel electrically. Tighten the cam set screw.

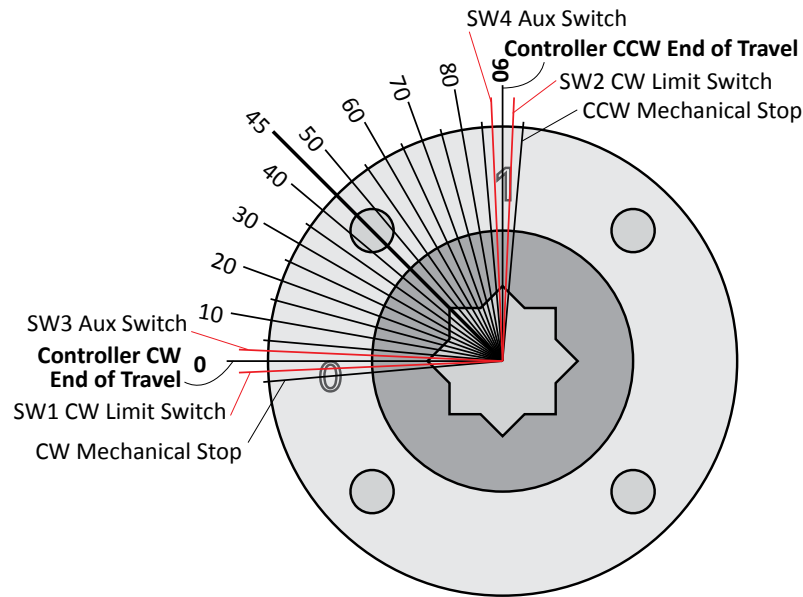
Adjust Cam 4 (SW4 -- CCW auxiliary switch)

1. The FOURTH cam is Cam 4, the CCW auxiliary switch (SW4) cam. When the actuator is in its CCW position set this cam. Use a 2.5mm hex key to free up the cam set screw. Once it is free, rotate the hex key to the LEFT 10-15 degrees to reset the switch roller arm. Then snug the set screw up against the camshaft (CW) until slight pressure is felt. Then SLOWLY rotate the hex key to the RIGHT until you hear the “click” on the fourth switch. Continue to rotate the cam between 3 and 5 degrees to the RIGHT to make sure the auxiliary cam switch changes state before the actuator reaches its end of travel electrically. Tighten the cam set screw.

Pre Calibration Preparation

This procedure will assume that the actuator is installed correctly both mechanically and electrically with correct **POWER** and **SIGNAL**, the cams are factory set 1-2° beyond 0° and 90°, and the mechanical stop screws are out.

Calibration - End of Travel, Feedback



This proportional control card has been calibrated and tested at the factory to operate between 0 degrees and 90 degrees operating range.

END OF TRAVEL

- Test the travel of the actuator with the handwheel by rotating from 0° to 90° and listen/feel for the change of state of the limit switches. If Cams 1 and 2 are outside the desired range of travel, skip step 2.
- Set cams per the **Setting Limit Switches and Auxiliary Switches (Cams)** section:
 - Cam 1 for approximately -1°.
 - Cam 3 for approximately 3°.
 - Cam 2 for approximately 91°.
 - Cam 4 cam for approximately 87°.

The open and close end of travel cams (Cam 1 and Cam 2) must be set outside the desired range of travel of the proportional card. If they trip, the proportional card stops the motor and reports a stall condition.

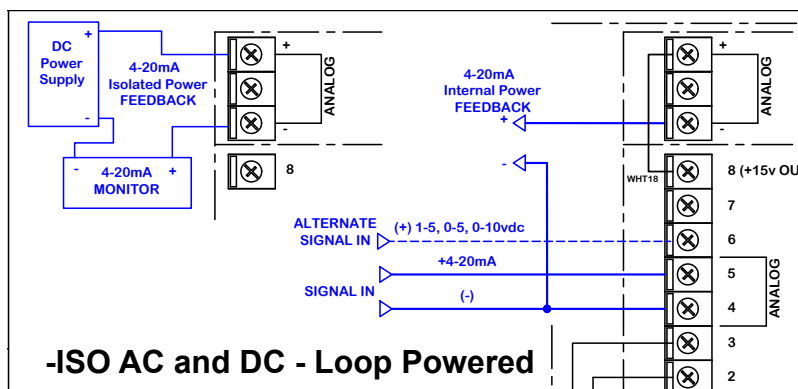
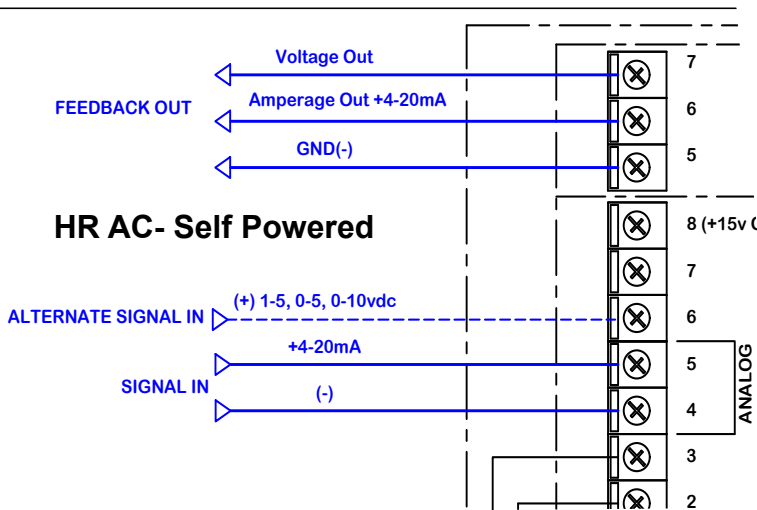
Connect Signal, Feedback and Power per wiring diagram:

- Signal - (Optional) 4-20mA in uses Terminal 5 (+) and 4 (-) and 0-10V in uses Terminals 7 (+) and 5(-) on J2

- Feedback - The HR feedback option for 24AC, 120AC and 230AC is self powered. 4-20mA out uses Terminal 6 (+) and 5 (-). 0-10V out uses Terminals 7 (+0 and 5(-). Use a known accurate meter to calibrate.

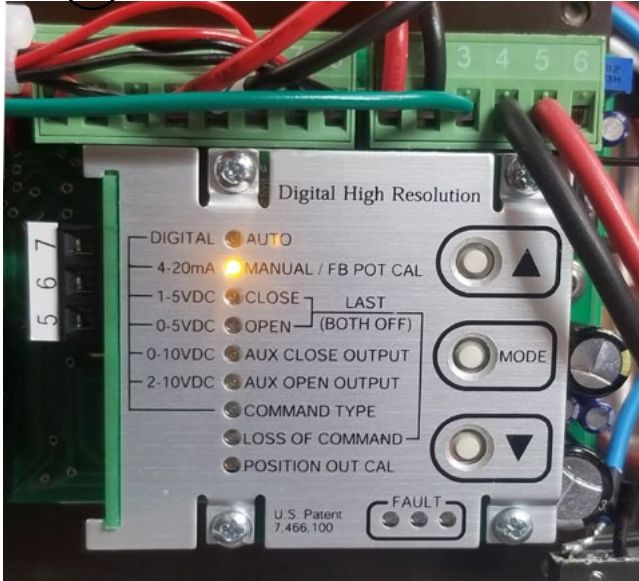
- Feedback - The HR-ISO option and feedback for all 12 and 24VDC controllers utilizes loop (external) power. The power can come from the board via terminal 8 or from an external power source.

- Apply line power.
- The AUTO green LED will light.
- The Red AUX POSITION OUT LED will blink if there is no control signal.



Calibrating the proportional control board

2



Calibration Interface Notes

The AUTO LED is lit during normal operation. Pressing MODE will enter the calibration sequence to change operational parameters. The MODE sequence goes in one direction. Each time MODE is pressed the current parameter is saved and the next one is presented. One can cycle through the operational parameters without changing them by pressing MODE repeatedly.

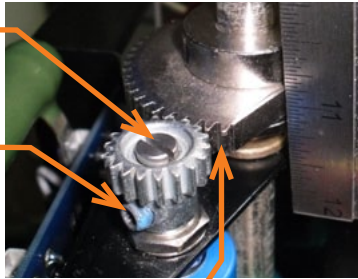
Begin Calibration

1. Apply Line Power - The AUTO green LED will light
2. Press MODE until MANUAL/FB POT CAL LED is lit.
 - You may calibrate this as often as needed but it may affect the CW and CCW end positions if it changes.
3. Use ▲ and ▼ or handwheel to position the actuator to the mid position (i.e. 50% open or 12 mA).
 - Blinking amber MANUAL/FB POT CAL light means you need to adjust the potentiometer position.

Potentiometer Shaft

Hex Screw

4

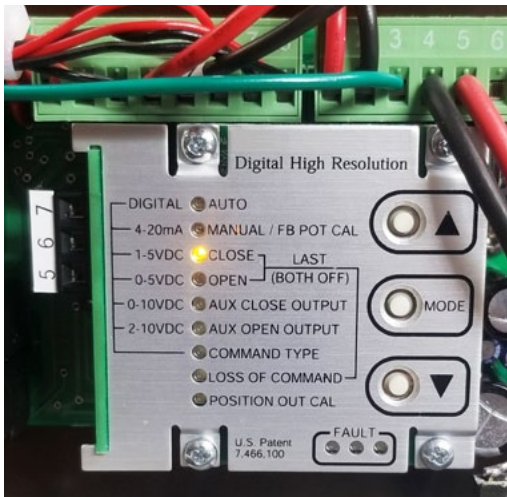


Potentiometer Gear Engagement

When the actuator is at CW position, the potentiometer pinion gear and the camshaft sector gear should not be past the point of engagement. If the sector gear should have at least 2 full teeth contacting the potentiometer pinion gear. If not, contact your distributor for mechanical recalibration instructions.

4. Feedback Potentiometer Calibration (FB POT CAL LED is blinking).
 - 4.A Check Potentiometer Gear Engagement as shown.
 - 4.B Loosen the potentiometer shaft hex screw. Use a screwdriver to adjust the potentiometer shaft until the amber LED is steady.

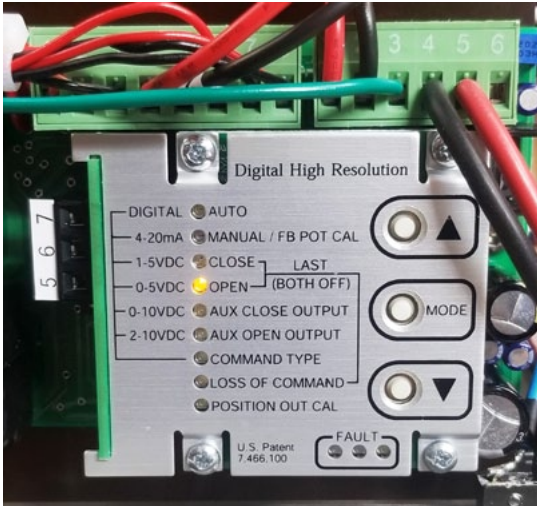
NOTE: The amber LED blinks more rapidly as you approach the proper mid position. The farther from that position, the slower the blinkrate.



5. Set Closed (CW) Position (CLOSE LED is lit)
 - 5.A The motor will drive to approximately the 25% position.
 - 5.B Use the handwheel or the ▲ and ▼ to position the actuator in the desired CLOSE position (i.e. 4 mA). (You must touch either ▲ or ▼ before the handwheel responds).
 - 5.C Press MODE to confirm setting. This will also move you to the next user input setting.
 - 5.D This CLOSE position is now set.
 - 5.E If the AUX CLOSE OUTPUT LED is lit, ignore it
 - 5.F OPEN LED is lit.

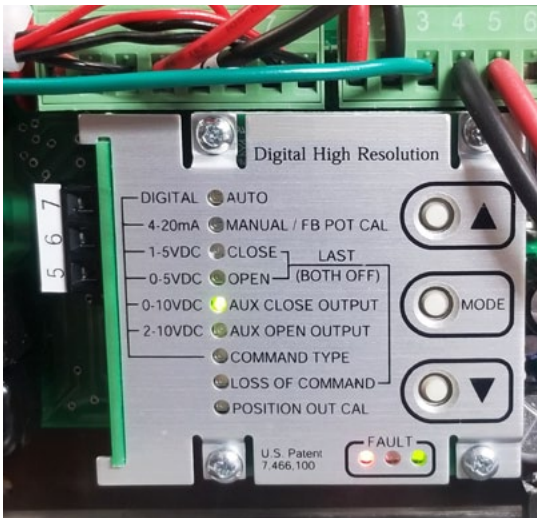
F:_Module\F_P2_P13\MS_Calibration\HWP\HWP\HWP\FZAKW100340228R\STER.Indd

Calibrating the proportional control board (continued)



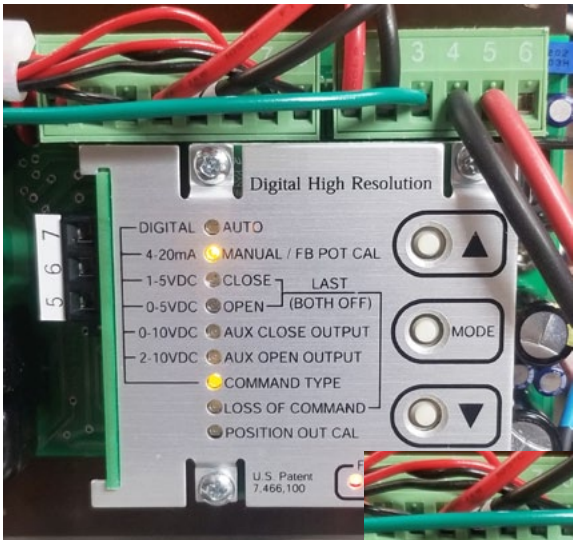
6. Set Open (CCW) Position (OPEN LED is lit)
 - 6.A The motor will drive to approximately the 75% position.
 - 6.B Use the handwheel or the ▲ and ▼ to position the actuator in the desired OPEN position (i.e. 20 mA). (You must touch either ▲ or ▼ before the handwheel responds).
 - 6.C Press MODE to confirm setting. This will also move you to the next user input setting.
 - 6.D This OPEN position is now set.
 - 6.E If the AUX OPEN OUTPUT LED is lit, ignore it.
 - 6.F AUX CLOSE OUTPUT is lit.

The motor may drive an arbitrary position.



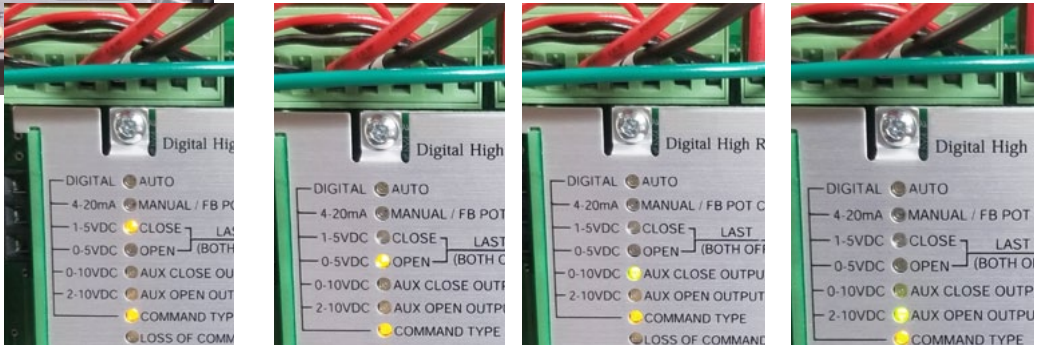
7. Aux Close Output Settings (AUX CLOSE OUTPUT is lit)
 - 7.A This feature requires an additional optional board.
 - 7.B Press MODE to skip.
 - 7.C AUX OPEN OUTPUT is lit.

The motor may drive an arbitrary position.



8. Aux Open Output Settings (AUX OPEN OUTPUT is lit)
 - 8.A This feature requires an additional optional board.
 - 8.B Press MODE to skip
 - 8.C COMMAND TYPE LED is lit.

9. Set Input Signal (COMMAND TYPE LED is lit)
 - 9.A Use ▲ and ▼ to select the command signal type going into the DHC-100 board from the column left of the LEDs.
 - 4-20mA (factory setting)
 - 1-5VDC
 - 0-5VDC
 - 0-10VDC
 - 9.B Press MODE to set Input Signal

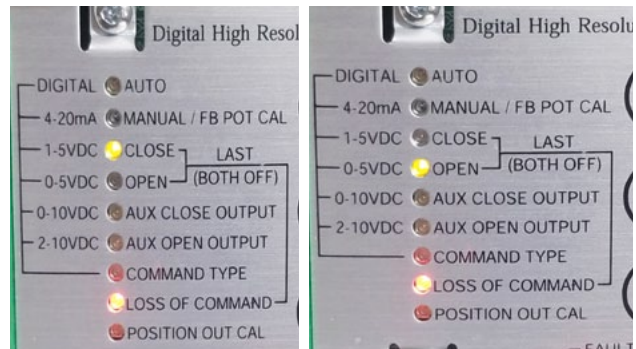


Calibrating the proportional control board (continued)



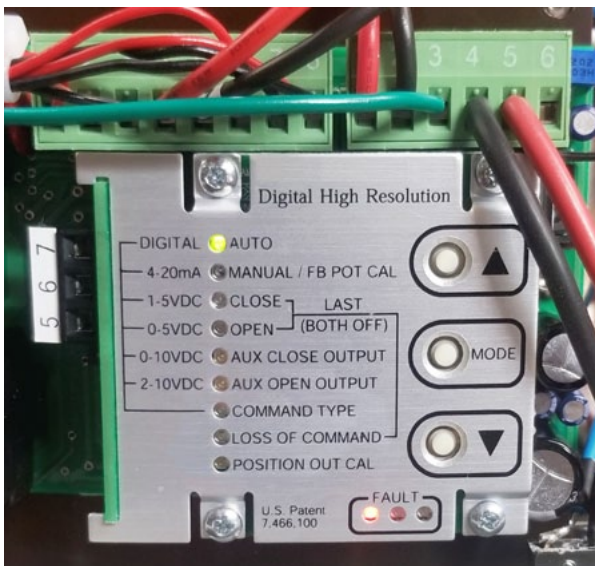
10. Set Loss of Signal (LOSS OF COMMAND LED is lit)
 - 10.A Use ▲ and ▼ to select the fail position on loss of signal. Select from the column right of the LEDs.
 - CLOSE - fails close (4mA)
 - OPEN - fails open (20mA)
 - (Both Off) - fails in place (default)
 - 10.B Press MODE to set
 - 10.C AUX POSITION OUT CAL LED is lit.

The motor may drive an arbitrary position.



11. Trim the accuracy of the feedback (AUX POSITION OUT CAL LED is lit)
 - 11.A The position of the actuator is unimportant for this step.
 - 11.B CLOSE LED should be flashing
 - 11.C Use ▲ and ▼ to adjust the mA feedback for the CLOSE position (i.e. 4.00mA). Read using a known accurate multimeter.
 - 11.D Press MODE to confirm setting.
 - 11.E OPEN LED should be flashing
 - 11.F Use ▲ and ▼ to adjust the mA feedback for the OPEN position (i.e. 20.000mA). This is read on a known accurate multimeter.
 - 11.G Press MODE to confirm setting,

Complete Calibration



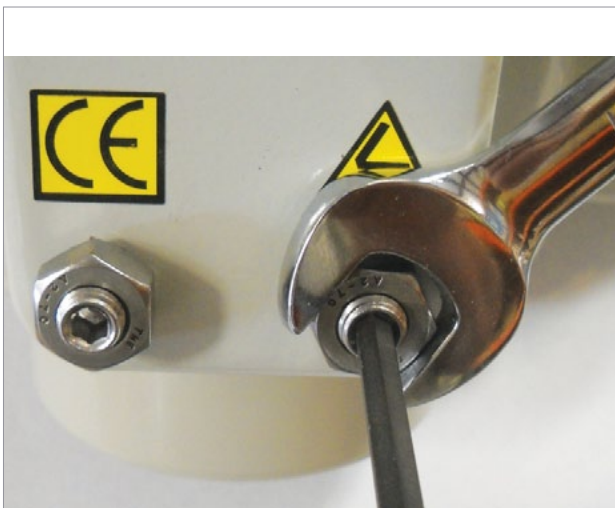
AUTO LED is lit. The actuator is now responding to the 4-20mA signal.

Calibration is complete.



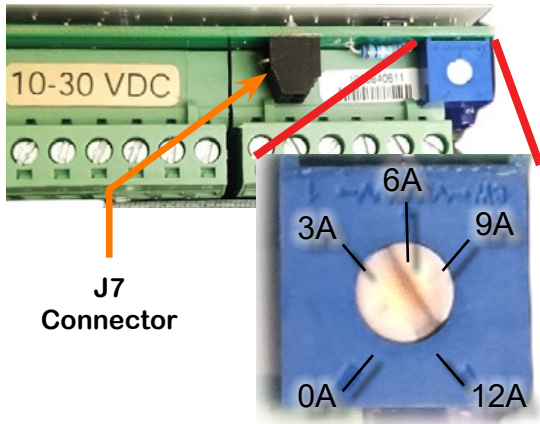
Reinstall mechanical stop screws.

- CCW Stop - drive to the OPEN position and power down actuator.
- With handwheel, drive more open until you hear the SW2 switch make.
- Drive the handwheel 1/2 turn more OPEN.
- Use wrench and hex key to install the CCW Stop screw on the stop boss.
- With the handwheel, insure the end stop is approximately 1/2 handwheel turn after the SW2 switch makes.



- CW Stop - drive to the CLOSE position and power down actuator.
- With handwheel, drive more close until you hear the SW1 switch make.
- Drive the handwheel 1/2 turn more CLOSE.
- Use wrench and hex key to install the CW Stop screw on the stop boss. With the handwheel, insure the end stop is approximately 1/2 handwheel turn after the SW1 switch makes.

Motor Amperage Limiter



The DC controllers are equipped with adjustable amperage limiting that is set by the rotational potentiometer adjacent to the J7 connector. The amperage draw on the motor is limited by the amperage setting as shown in the inset. The setting should be adjusted to a reasonable level above the running current expected for the actuator and its load. When the motor current exceeds the trip setting, the motor is turned off and a Current Trip fault condition is indicated.

The amperage limiter setting essentially performs the same function as torque switches. The limiter is for the actuator motor, so other components in the system (gears, couplings, packing, seats, etc.) also place a load on the motor. The effect of these components will vary with temperature and age. Therefore the amperage draw on the motor may vary accordingly.

The J7 Connector is used in conjunction with local control stations (LCS) or motor control stations (MCC) for local control of the actuator. Both AC and DC controllers contain the J7 connector

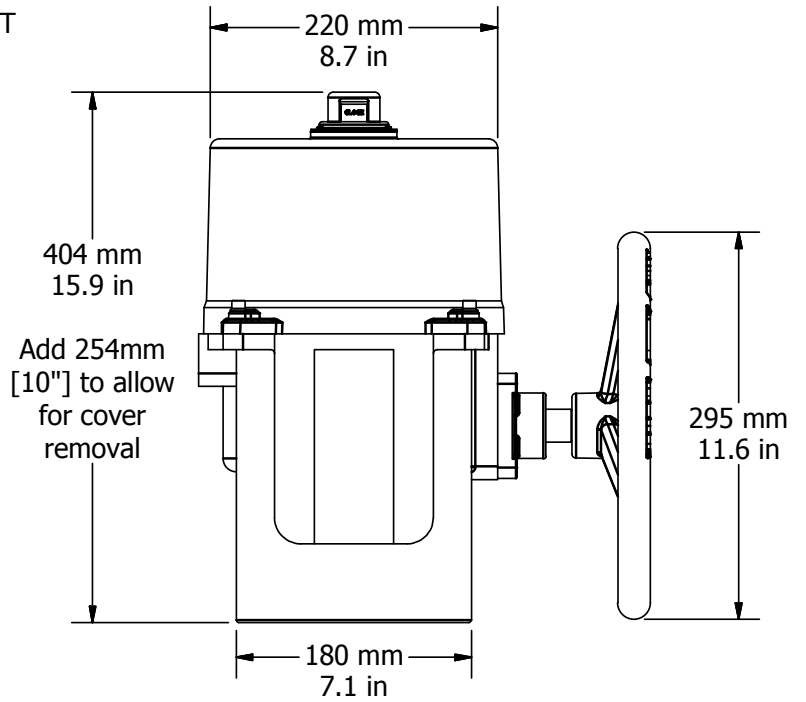
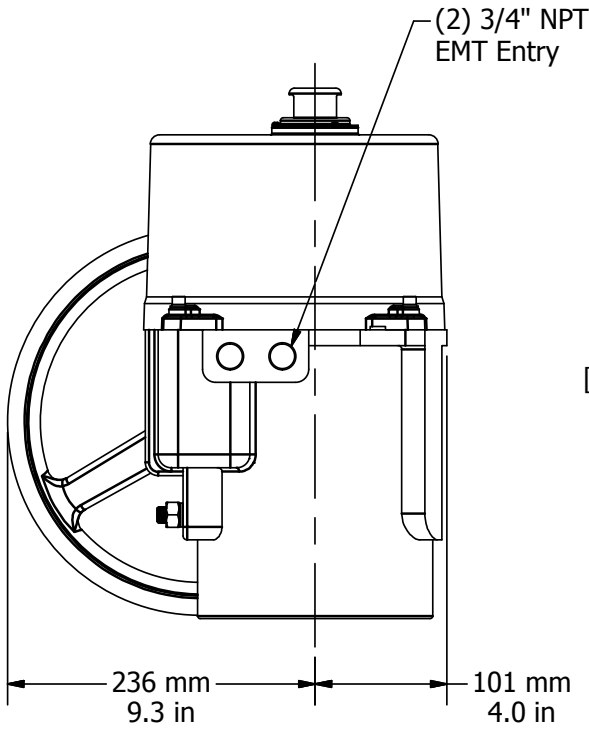
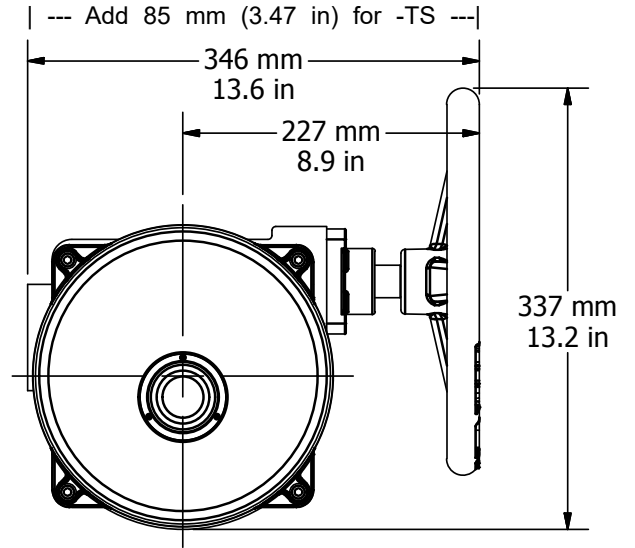
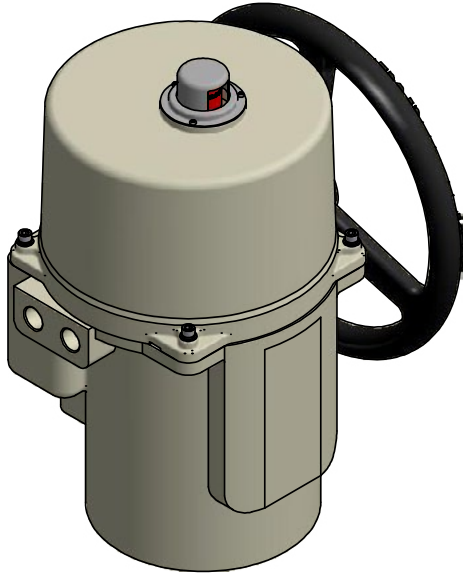
FAULT INDICATORS

RED	YEL	GRN	FAULT	12, 24 VDC	24, 120, 230 VAC	
flash	OFF	OFF	Low Voltage	X		Supply voltage is less than 10VDC
flash	flash	OFF	Motor 1 Stall	X	X	No motor movement in direction 1 upon command with motor amperage load
flash	OFF	flash	Motor 2 Stall	X	X	No motor movement in direction 2 upon command with motor amperage load
flash	flash	flash	Double Stall	X		No motor in either direction movement upon command
flash	ON	OFF	Motor 1 Current Trip	X		Current on motor line 1 is higher than current trip setting
flash	OFF	ON	Motor 2 Current Trip	X		Current on motor line 2 is higher than current trip setting
flash	ON	ON	Double Current Trip	X		Current too high in both motor directions
ON	OFF	OFF	Over Voltage	X		Supply voltage is higher than 30VDC
ON	flash	OFF	Motor 1 No Motion	X		No motor movement in direction 1 upon command with no motor amperage load
ON	OFF	flash	Motor 2 No Motion	X		No motor movement in direction 2 upon command with low motor amperage load
ON	flash	flash	Double No Motion	X		No motor movement in either direction upon command with low motor amperage load
OFF	OFF	flash	Feedback Alarm	X	X	Feedback signal from potentiometer out of range or not present
OFF	flash	OFF	Loss of Command	X	X	Command signal is disconnected
OFF	ON	OFF	Command Out of Range	X	X	Command signal is out of range
OFF	flash	flash	Feedback Alarm and Loss of Command	X	X	Both potentiometer and command signals are lost
OFF	ON	flash	Feedback Alarm and Command Out of Range	X	X	Potentiometric signal is lost, command signal is out of range

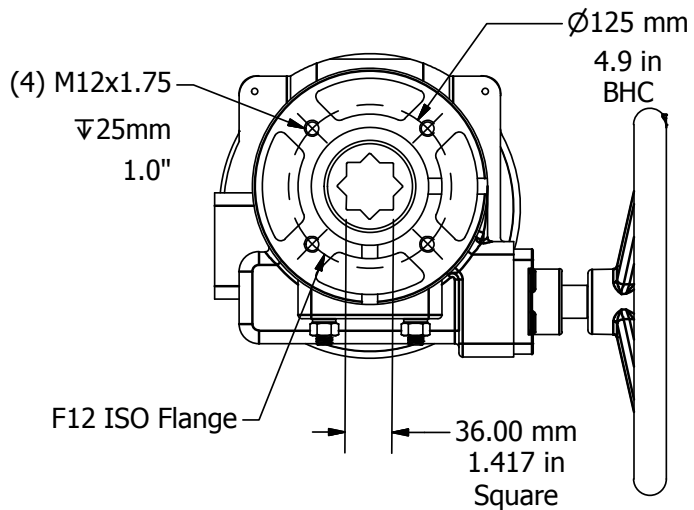
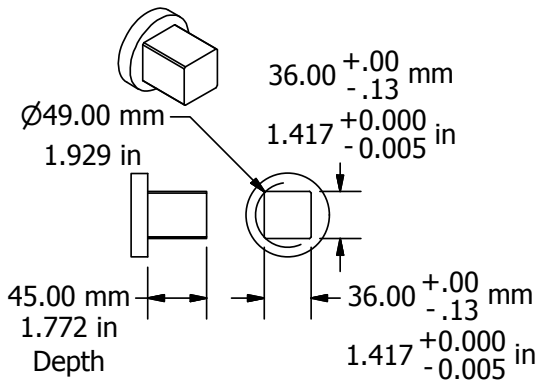
FM1_Module_P2_P23_PMS_Controller_HR(-TS)_Series_PZAKen1@340028RMASTER.indd

Mechanical Data

P7/8 Series Dimensional Data



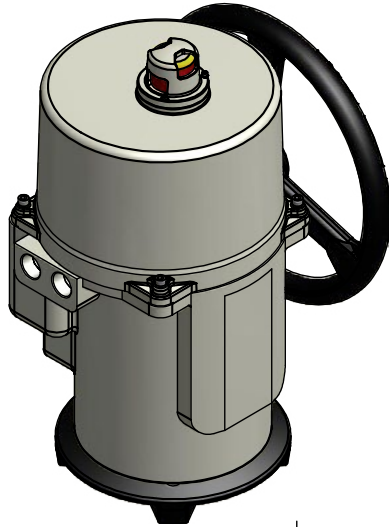
Drive Coupling Fabrication Data



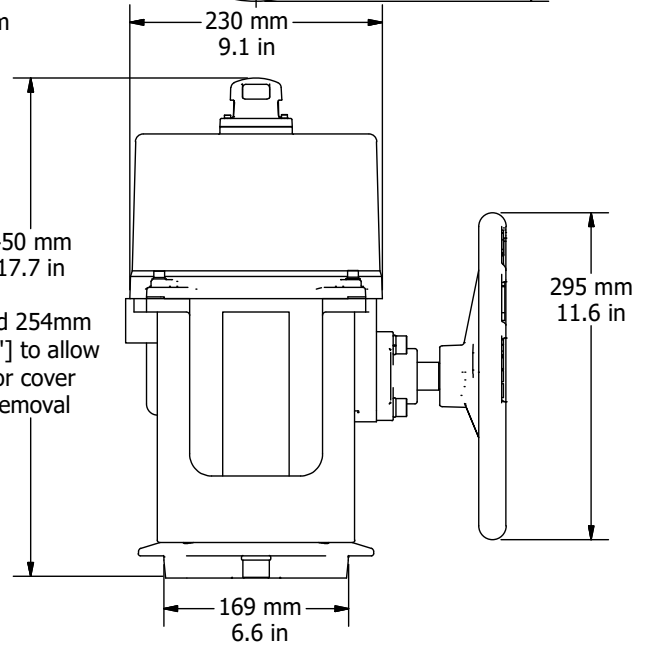
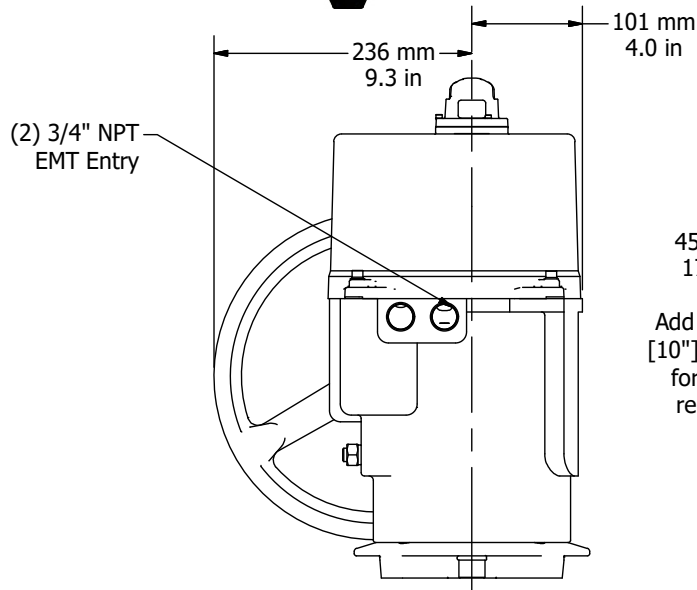
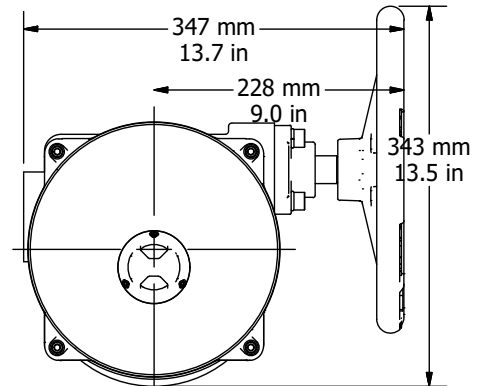
FM_P213 ISO HV-PN4-HR (-TS) N7_Ver Q 080223

Mechanical Data

P7/8Series Dimensional Data Imperial Mount

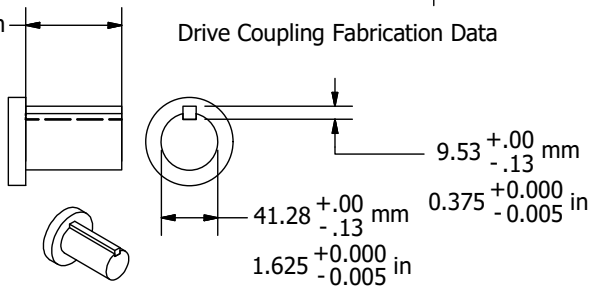


| --- Add 85 mm (3.47 in) for -TS ---|

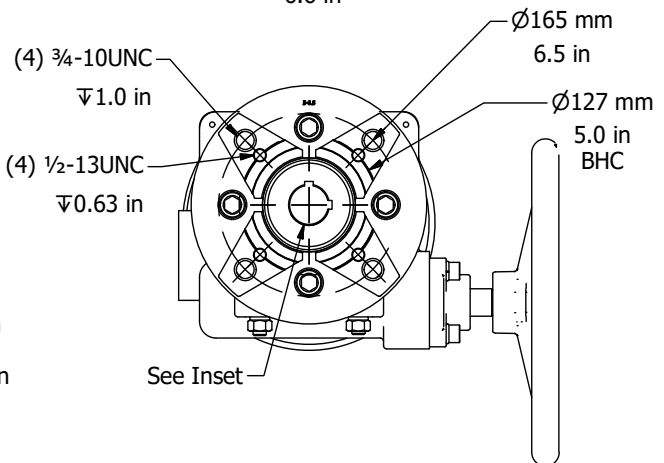
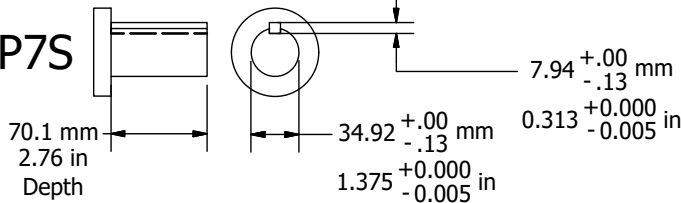


70.1 mm 2.76 in Depth
Drive Coupling Fabrication Data

P8S



P7S

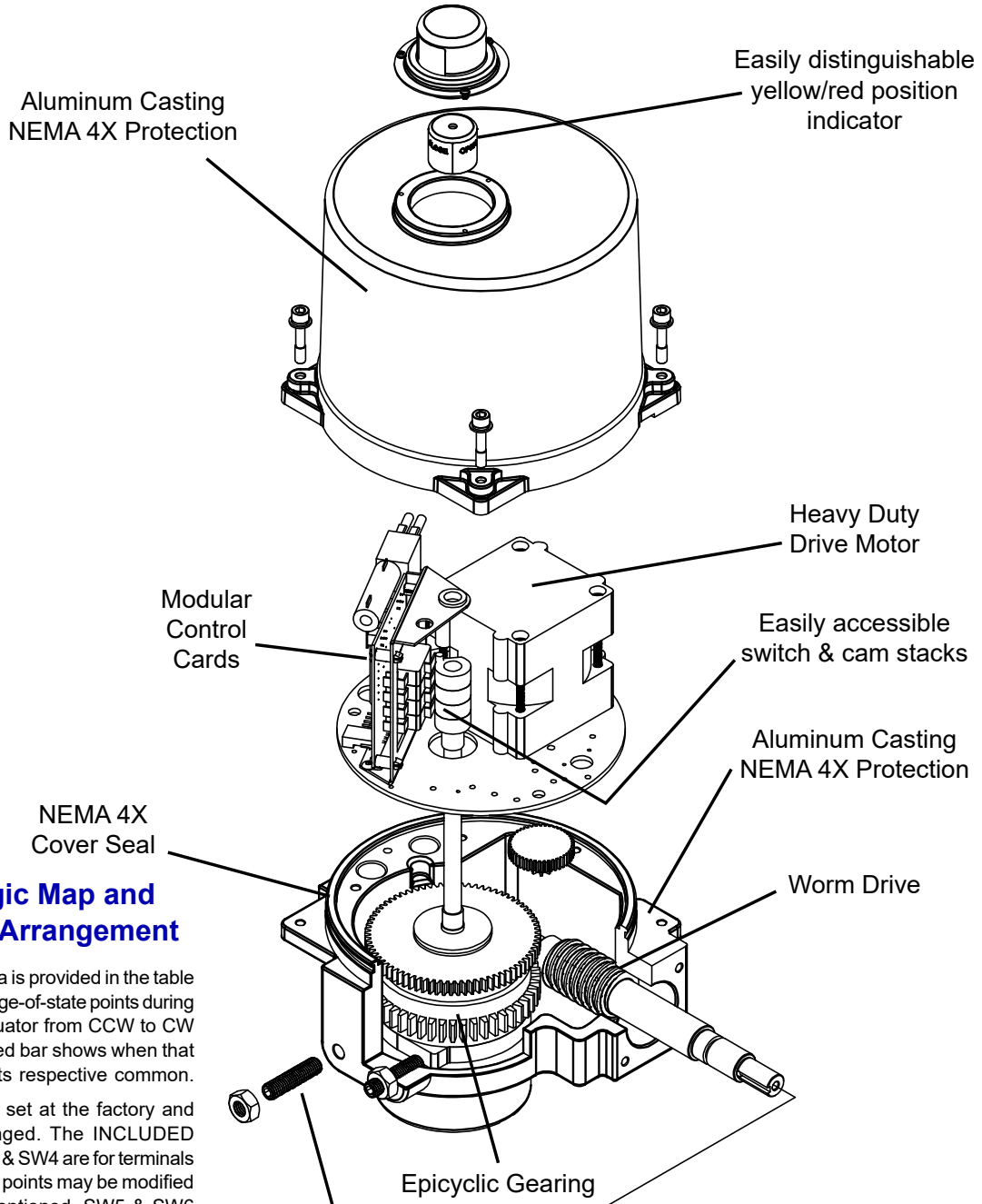


FM_P213 ISO HV-PPN4-HR (-TS) NZ_Ver Q 080223

Mechanical Data

P Series Exploded View

(P2/3-120N4 unit is shown)



Switch Logic Map and Switch/Cam Arrangement

Switch sequencing data is provided in the table below to show the change-of-state points during the rotation of the actuator from CCW to CW and back again. The red bar shows when that terminal makes with its respective common.

Switches 1 and 2 are set at the factory and should NOT be changed. The INCLUDED auxiliary switches SW3 & SW4 are for terminals 7 thru 12 and those set points may be modified if need be. When so optioned, SW5 & SW6 auxiliary switches are initially set to function the same as auxiliary switches SW3 & SW4.

	cw			ccw		
	-5°	0°	5°	85°	90°	95°
12	Not Open					
11	Open Switch Common					
10	Open					
9	Not Closed					
8	Closed Switch Common					
7	Closed					

SW4 CCW AUX
(Factory Set - Adj)

SW3 CW AUX
(Factory Set - Adj)

Used by
Controller

FM_P213 ISO HV-PN4-HR (-TS) N7_Ver Q 080223

Commissioning

After completing all mounting and wiring procedures and main power is available, it is now possible to commission the actuator.

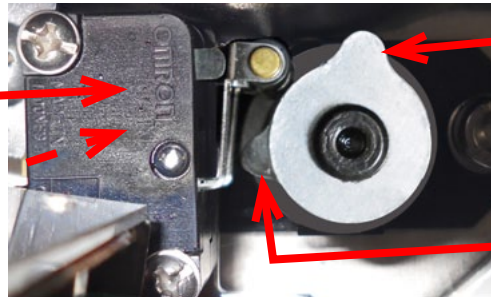
1. Utilize the handwheel to rotate the actuator and damper, valve or other connected device through its full travel from full CW to full CCW and back again to check for any possible interference. Do NOT utilize any mechanical advantage devices to rotate the handwheel (pipes, wrenches, extension bars, etc.).
2. Manually position the actuator to its mid-stroke position.
3. Make certain the 3 wire orange plug is fully seated on the 3-pin receptacle on the switch board.
4. Apply correct power to the unit.
5. Measure correct power on terminals 1 and 2 on the switch board.
6. Measure correct power on the two heater terminals on the switch board.
7. Command the field device to generate a CCW signal. The actuator rotates in a CCW direction (as viewed from above).
8. Actuator will stop when it reaches it's full CCW position.
9. Command the field device to generate a CW signal. The actuator rotates in a CW direction (as viewed from above).
10. Actuator will stop when it reaches it's full CW position.
11. Generate a mid-position signal at the field device to move the actuator off its full CW trip position.
12. Actuators with no -TS options are now commissioned and operational. See below for additional -TS steps.

Commissioning for TS units

TS units incorporate a torque overload protection system. In NORMAL operating mode, the torque switch drive cam is in this position:

WARNING! Do NOT adjust the torque switch cam settings. This will VOID the warranty.

High Torque Switch (top) for CW Output Drive Rotation
 High Torque Switch (bottom) for CCW Output Drive Rotation



High Torque Cam (top) for CW Output Drive Rotation
 High Torque Cam (bottom) for CCW Output Drive Rotation

Torque Switch cams shown in the NORMAL operating position (No high torque situations)

Testing Torque Switch Electrical Operation



Test Torque Switch functions

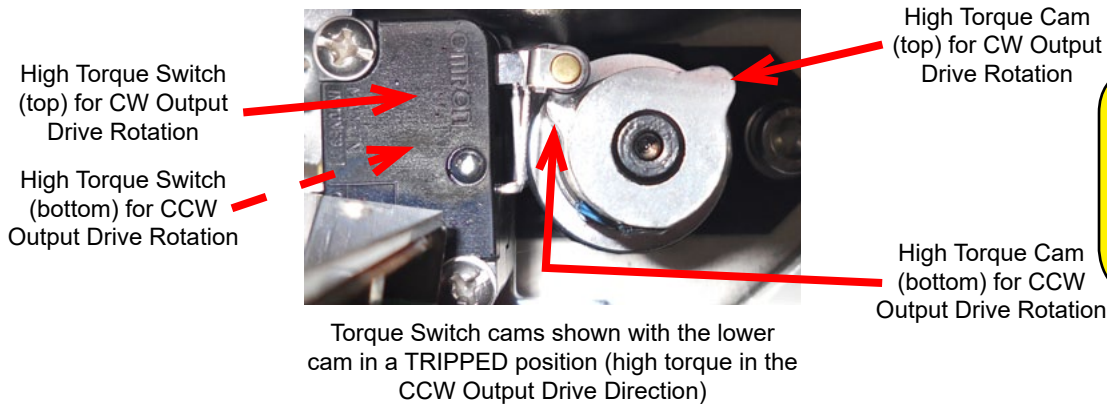
1. Generate a 4mA or 20mA control signal and let the actuator drive towards that CW or CCW position.
2. As the motor is running, simulate a torque switch event: Depress the top or bottom torque switch and hold it (one will immediately stop the motor).
3. Release the torque switch.
4. Test recovery from the torque switch event.
 - Move the handwheel 2° in either direction
 - Signal the motor to drive.
5. Repeat steps 1 through 4 in the opposite direction (20mA or 4mA) to test the opposing direction torque switch functionality.

FM_P213 ISO HV/PN4-HR (-TS) NZ_Ver Q 080223

Commissioning for TS units (continued)

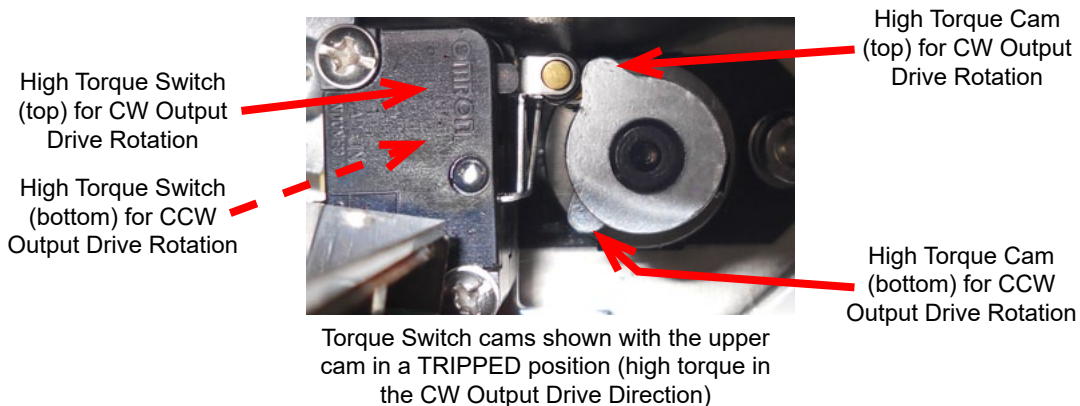
Test Torque Switch CCW Mechanical Operation

1. Rotate the manual override handwheel in a CCW direction to continue to drive the output drive in a CCW direction until the drive system reaches the end of its MECHANICAL travel either by coming into contact with the mechanical stop screw OR it reaches the end of the valve (or damper) travel. This is indicative of an increasing force required to rotate the handwheel.
2. At this point the torque switch cam shaft starts to rotate in a CW direction. (There is no need to continue to rotate the handwheel further in the CCW direction, the torque switch cam shaft would continue to rotate in the CW direction until the LOWER cam trips the LOWER high torque switch).
3. At this point, stop rotating the handwheel as you've simulated reaching the electrical drive limit of the actuator under excessively high torque situations in the CCW output drive direction.



Test Torque Switch CW Mechanical Operation

1. Rotate the manual override handwheel in a CW direction to continue to drive the output drive in a CW direction until the drive system reaches the end of its MECHANICAL travel either by coming into contact with the mechanical stop screw OR it reaches the end of the valve (or damper) travel. This is indicative of an increasing force required to rotate the handwheel.
2. At this point the torque switch cam shaft starts to rotate in a CCW direction. (There is no need to continue to rotate the handwheel further in the CW direction, the torque switch cam shaft would continue to rotate in the CCW direction until the UPPER cam trips the UPPER high torque switch).
3. At this point, stop rotating the handwheel as you've simulated reaching the electrical drive limit of the actuator under excessively high torque situations in the CW output drive direction.



4. Generate a mid-position signal at the field device to move the actuator off its full CW trip position.
5. Actuator is now commissioned and operational.

